

Jeri "abbiamo visto"
che per ogni $n \geq 1$
la funzione

$d^{(n)} : \text{Mat}_{n \times n}(\mathbb{K}) \rightarrow \mathbb{K}$
definite come

$$d^{(1)} = \text{Id}_{\mathbb{K}}$$

$$d^{(n)}(A) = \sum_{k=1}^n (-1)^{k+1} a_{k1} d^{(n-1)}(A_{k1})$$

è multilineare e
alternante sulle righe
 $d^{(n)}(\mathbb{1}_n) = d^{(n)}(e_1^t, \dots, e_n^t)$
 $= 1$

Equivalentemente,

$$d^{(n)}(P_{ij}A) = -d^{(n)}(A)$$

$$d^{(n)}(D_i(\lambda)A) = \lambda d^{(n)}(A)$$

$$d^{(n)}(F_{ij}(c)A) = d^{(n)}(A)$$

$\forall A \in \text{Mat}_{n \times n}(\mathbb{K}), \forall i \neq j,$
 $\forall \lambda, c \in \mathbb{K}, \lambda \neq 0.$

$$d^{(2)}\begin{pmatrix} a & b \\ c & d \end{pmatrix} = ad - bc$$

$$d^{(2)}\begin{pmatrix} a & b \\ a & b \end{pmatrix} = ab - ab = 0$$

$$d^{(2)}\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = 1$$

Teorema (unicità del determinante)

Sia $f: \text{Mat}_{n \times n}(\mathbb{K}) \rightarrow \mathbb{K}$ t.c.

$$f(P_{ij}A) = -f(A)$$

$$f(D_i(\lambda)A) = \lambda f(A)$$

$$f(F_{ij}(c)A) = f(A)$$

$\forall A \in \text{Mat}_{n \times n}(\mathbb{K}), \forall i \neq j,$

$\forall \lambda, c \in \mathbb{K}, \lambda \neq 0$

ed inoltre

$$f(\mathbb{1}_n) = 1.$$

Allora $f = d^{(n)}$.

dim: Sia $A \in \text{Mat}_{n \times n}(\mathbb{K})$
e dimostriamo che

$$f(A) = d^{(n)}(A).$$

$$A \underset{R}{\sim} R = \text{rref}(A)$$

$R = E_k \cdots E_1 A$ per
opportune matrici
elementari E_1, \dots, E_k .

$$A = E_1^{-1} \cdots E_k^{-1} R$$

Poiché

$$P_{ij}^{-1} = P_{ij}$$

$$D_i(\lambda)^{-1} = D_i\left(\frac{1}{\lambda}\right)$$

$$F_{ij}(c)^{-1} = F_{ij}(-c)$$

l'inversa di una matrice el.

\bar{e} è una matrice elementare.

$$A = F_1 \cdots F_k R$$

dove F_1, \dots, F_k sono matrici elementari.

$$f(A) = c f(R)$$

dove c è una costante che non dipende da f ma solo dalle operazioni elementari svolte per trasformare A in R .

$R \begin{cases} \rightarrow \textcircled{1} \text{ L'ultima riga di } R \\ \text{è nulla} \\ \rightarrow \textcircled{2} R = \mathbb{1}_m \end{cases}$

$$\textcircled{1} \Leftrightarrow \text{rg} A < m$$

$$\textcircled{2} \Leftrightarrow \text{rg} A = m \Leftrightarrow A \text{ inv.}$$

$$f(A) = c f(R)$$

$$= \begin{array}{c} \textcircled{1} \\ \hline 0 \end{array}$$

$$\begin{array}{c} \textcircled{2} \\ \hline c \end{array}$$

similmente,

$$d^{(m)}(A) = \begin{array}{c} \textcircled{1} \\ \hline 0 \end{array}$$

$$\begin{array}{c} \textcircled{2} \\ \hline c \end{array}$$

$$f(A) = d^{(m)}(A)$$

▣

COR: Sia V un K -sp. vett.

Sia $B = (v_1, \dots, v_m)$ una base di V .

Sia $f: \underbrace{V \times \dots \times V}_{n = \dim V} \rightarrow K$

t.c. f è multilineare, alternante e

$$f(v_1, \dots, v_m) = 1.$$

Allora tale f esiste ed è unica, più precisamente

$$f(w_1, \dots, w_n) = \det(F_B(w_1)^t, \dots, F_B(w_n)^t) \quad (*)$$

dim: Sia f definita da (*).

Vediamo che f è

• multilineare:

$$f(-, \alpha u + \beta w, -) \stackrel{(*)}{=}$$

$$= \det(-, F_B(\alpha u + \beta w)^t, -)$$

F_B e t sono lineari

$$= \det(-, \alpha F_B(u)^t + \beta F_B(w)^t, -)$$

\det è multilineare

$$= \alpha \det(-, F_B(u)^t, -) +$$

$$+ \beta \det(-, F_B(w)^t, -).$$

$$= \alpha f(-, u, -) + \beta f(-, w, -).$$

• alternante

$$f(-, w, -, w, -) =$$

$$= \det(-, F_{\mathcal{B}}(w)^t, -, F_{\mathcal{B}}(w)^t, -)$$

$$= 0$$

• $f(v_1, \dots, v_m) =$

$$= \det(F_{\mathcal{B}}(v_1)^t, \dots, F_{\mathcal{B}}(v_m)^t)$$

$$= \det(e_1^t, \dots, e_n^t) = \det(\mathbb{1}_n) = 1.$$

Sia $g: V \times \dots \times V \rightarrow \mathbb{K}$
multilineare, alternante
 $g(v_1, \dots, v_n) = 1$.

Dimostriamo che

$$g(w_1, \dots, w_n) = \det(F_{\mathcal{B}}(w_1)^t, \dots, F_{\mathcal{B}}(w_n)^t)$$

Consideriamo la f.m.e

$g': \text{Mat}_{n \times n}(\mathbb{K}) \rightarrow \mathbb{K}$
definita come segue

$$g'(X_1, \dots, X_n) :=$$

$$= g(F_{\mathcal{B}}^{-1}(X_1^t), \dots, F_{\mathcal{B}}^{-1}(X_n^t)).$$

g' è multilineare e
alternante sulle righe

$$g'(e_1^t, \dots, e_n^t) = 1. \text{ [Esercizio!]}$$

$$\Rightarrow g'(x_1, \dots, x_n) = \\ = \det(x_1, \dots, x_n)$$

$$g(w_1, \dots, w_n) = \\ = g'(F_B(w_1)^t, \dots, F_B(w_n)^t) \\ = \det(F_B(w_1)^t, \dots, F_B(w_n)^t)$$

□

Tale f.ne si chiama
determinante

$$\det : V \times \dots \times V \rightarrow K$$

(dipende dalla scelta di
una base di V).

Determinante 2x2 come
area "orientata".

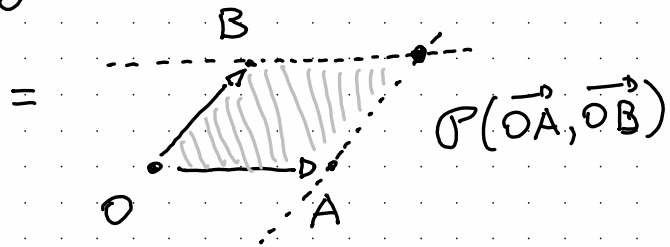
$$\text{Sia } V = V_0^2 = \{\vec{OP} \mid P \in \mathbb{E}^2\}$$

Una base $B = (\vec{OA}, \vec{OB})$ di V
è unitaria se

$$\text{Area } P(\vec{OA}, \vec{OB}) = 1$$

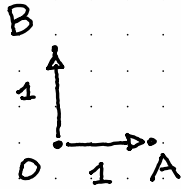
dove

$P(\vec{OA}, \vec{OB}) =$ parallelogramma
generato da \vec{OA} e $\vec{OB} =$

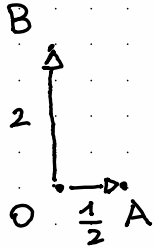


Es:

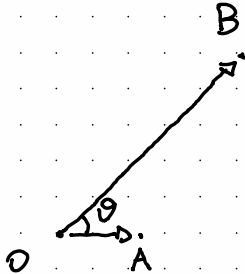
.)



.)

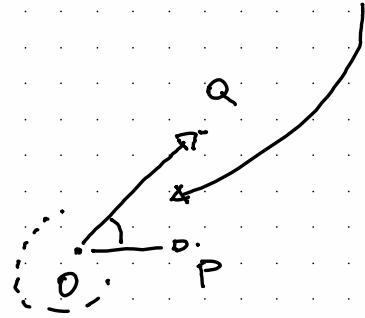


.)



$$\text{Area } \mathcal{P}(\vec{OP}, \vec{OQ}) =$$

$$= |\vec{OP}| |\vec{OQ}| \sin \hat{POQ}$$



Teorema:

Sia B una base unitaria
di V_0^2 . Allora

$$\text{Area}(\mathcal{P}(\vec{OP}, \vec{OQ})) = \left| \det(F_B(\vec{OP})^t, F_B(\vec{OQ})^t) \right|$$

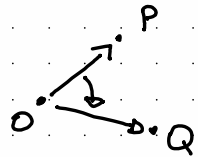
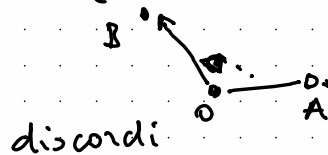
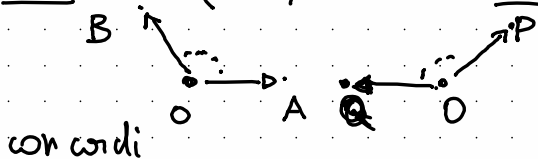
dim: Sia

$$A: V_0^2 \times V_0^2 \longrightarrow \mathbb{R}$$

definita come

$$A(\vec{OP}, \vec{OQ}) = \begin{cases} \text{Area}(\mathcal{P}(\vec{OP}, \vec{OQ})) & \text{se } (\vec{OP}, \vec{OQ}) \text{ \u00e9 concorde} \\ & \text{con } B \\ -\text{Area}(\mathcal{P}(\vec{OP}, \vec{OQ})) & \text{se } (\vec{OP}, \vec{OQ}) \text{ non \u00e9} \\ & \text{concorde con } B \end{cases}$$

dove: (\vec{OP}, \vec{OQ}) \u00e9 concorde con (\vec{OA}, \vec{OB}) se



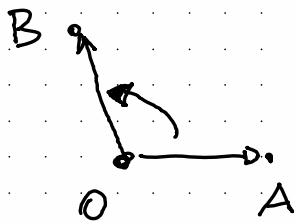
Coppie concordi di vettori geometrici:



Anti-orario

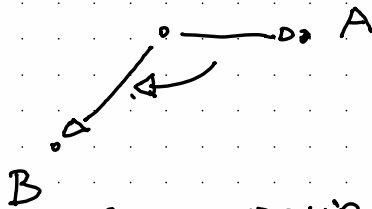


orario



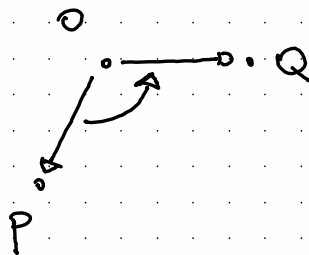
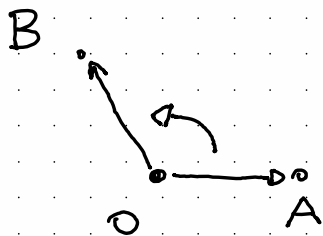
(\vec{OA}, \vec{OB})

senso
anti-orario

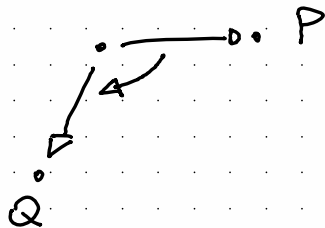
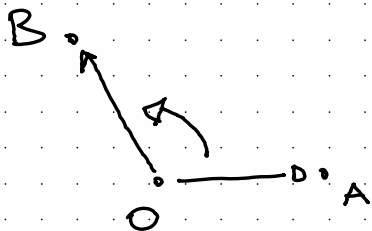


senso orario

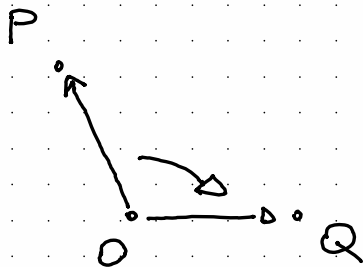
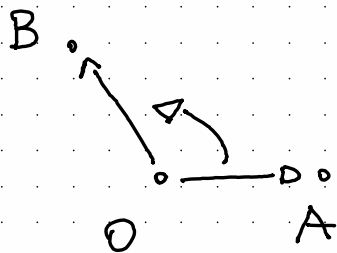
(\vec{OA}, \vec{OB}) e (\vec{OP}, \vec{OQ}) è concorde se l'angolo da \vec{OA} a \vec{OB} e da \vec{OP} a \vec{OQ} è per entrambi orario o per entrambi anti-orario.



(\vec{OA}, \vec{OB}) e (\vec{OP}, \vec{OQ}) sono concordi.



(\vec{OA}, \vec{OB}) e (\vec{OP}, \vec{OQ}) sono discordi.



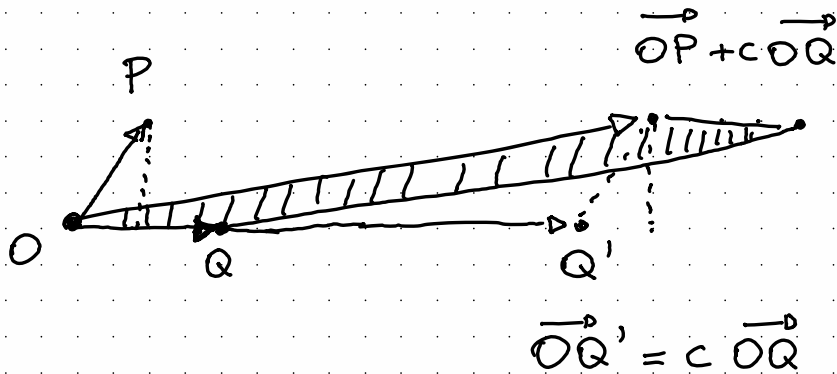
(\vec{OA}, \vec{OB}) e (\vec{OP}, \vec{OQ}) sono discordi.

Dimostriamo che A è multilineare, alternante e vale 1 sugli elementi di B .

• Sia $c > 0$

$$A(\vec{OP} + c\vec{OQ}, \vec{OQ}) \stackrel{?}{=} A(\vec{OP}, \vec{OQ})$$

$$\text{Area}(\mathcal{P}(\vec{OP} + c\vec{OQ}, \vec{OQ})) = \text{Area}(\mathcal{P}(\vec{OP}, \vec{OQ}))$$



$$\begin{aligned} & \rightarrow A(c\vec{OP}, \vec{OQ}) \\ &= c A(\vec{OP}, \vec{OQ}) \end{aligned}$$

$$\begin{aligned} & \rightarrow B = (\vec{OA}, \vec{OB}) \\ & A(\vec{OA}, \vec{OB}) = 1 \end{aligned}$$

$$\text{Area}(\mathcal{P}(\vec{OP}, \vec{OQ})) = \text{Area}(\mathcal{P}(\vec{OQ}, \vec{OP}))$$

$$\rightarrow A(\vec{OQ}, \vec{OP}) = -A(\vec{OP}, \vec{OQ})$$

Per il corollario

$$A(\vec{OP}, \vec{OQ}) = \det(F_B(\vec{OP})^t, F_B(\vec{OQ})^t)$$

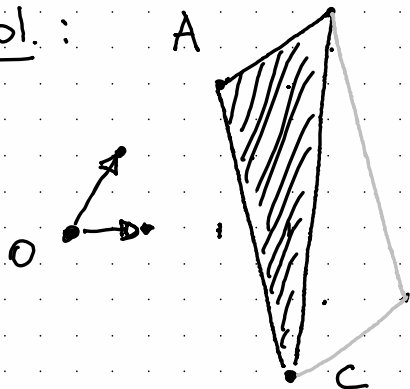
▮

Es: Sia B una base unitaria di V_0^2 .

Calcolare l'area del triangolo di vertici $A, B, C \in E^2$ dove

$$F_B(\vec{OA}) = \begin{pmatrix} 1 \\ 2 \end{pmatrix}, F_B(\vec{OB}) = \begin{pmatrix} 2 \\ 3 \end{pmatrix}, F_B(\vec{OC}) = \begin{pmatrix} 4 \\ -2 \end{pmatrix}$$

Sol.:



$$\text{Area}(T) = \frac{1}{2} \text{Area } P(\vec{AC}, \vec{AB})$$
$$\vec{AC} = \vec{OC} - \vec{OA}, \vec{AB} = \vec{OB} - \vec{OA}$$

$$= \frac{1}{2} \left| \det(F_B(\vec{OC} - \vec{OA})^t, F_B(\vec{OB} - \vec{OA})^t) \right|$$

$$= \frac{1}{2} \left| \det \begin{pmatrix} 3 & -4 \\ 1 & 1 \end{pmatrix} \right| = \frac{1}{2} |3+4| = \frac{7}{2}$$

▮

Tecniche di calcolo

$$\det(A) = ?$$

$$A \rightsquigarrow S \rightsquigarrow \text{rref}(A)$$

Prop.: Sia

$$S = \begin{pmatrix} s_{11} & s_{12} & \dots & s_{1n} \\ 0 & s_{22} & & \\ \vdots & \vdots & \ddots & \vdots \\ 0 & & & s_{nn} \end{pmatrix}$$

una matrice $n \times n$ a scale.

Allora

$$\det(S) = s_{11} s_{22} \dots s_{nn}$$

□
(Lmedi')

Es:

$$\det \begin{pmatrix} 2 & 1 & 1 \\ 2 & 1 & 0 \\ 3 & -1 & 1 \end{pmatrix} =$$

$$= 2 \det \begin{pmatrix} 1 & \frac{1}{2} & \frac{1}{2} \\ 2 & 1 & 0 \\ 3 & -1 & 1 \end{pmatrix}$$

$$= 2 \det \begin{pmatrix} 1 & \frac{1}{2} & \frac{1}{2} \\ 0 & 0 & -1 \\ 0 & -\frac{5}{2} & -\frac{1}{2} \end{pmatrix}$$

def di $d^{(3)}$.

$$\downarrow \\ = 2 \det \begin{pmatrix} 0 & -1 \\ -\frac{5}{2} & -\frac{1}{2} \end{pmatrix}$$

$$= -2 \det \begin{pmatrix} -\frac{5}{2} & -\frac{1}{2} \\ 0 & -1 \end{pmatrix} \stackrel{\text{Prop}}{=} \downarrow$$

$$= -2 \left(-\frac{5}{2}\right)(-1) = -5. \quad \square$$