

Richiami: Il determinante è una funzione

$$\det = \det^{(n)} : \text{Mat}_{n \times n}(\mathbb{K}) \longrightarrow \mathbb{K}$$

tale che

$$\det(P_{ij} A) = -\det(A)$$

$$\det(D_i(\lambda) A) = \lambda \det(A)$$

$$\det(F_{ij}(c) A) = \det(A)$$

$$\det(\mathbb{1}_n) = 1$$

} multilineare +  
alternante sulle righe

Prop.:  $\det(A) \neq 0 \iff \text{rref}(A) = \mathbb{1}_n \iff A$  è invertibile.

$$\det \begin{pmatrix} a_{11} & * & \dots & * \\ 0 & a_{22} & & \\ \vdots & \vdots & \ddots & \vdots \\ 0 & \dots & 0 & a_{nn} \end{pmatrix} = a_{11} a_{22} \dots a_{nn}$$

$$\det^{(n)}(A) = \sum_{j=1}^n a_{ij} \underbrace{\det^{(n-1)}(A_{ij})}_{C_{i,j}} (-1)^{i+j} : \text{Sviluppo di Laplace delle righe } i.$$

operazioni elementari sulle colonne:

$$\left. \begin{array}{l}
 A \xrightarrow{C^i \leftrightarrow C^j} A P_{ij} \\
 A \xrightarrow{C^i \mapsto \lambda C^i} A D_i(\lambda) \\
 A \xrightarrow{C^i \mapsto C^i + \mu C^j} A F_{ji}(\mu)
 \end{array} \right\} \Leftrightarrow (AB)^t = B^t A^t$$

$$3) \det(A) = \sum_{i=1}^n a_{ij} \det(A_{i,j}) (-1)^{i+j} :$$

Sviluppo di  
Laplace della  
colonna  $j$ .

Teorema : 1)  $\text{rg}(A^t) = \text{rg}(A)$

2)  $\det(A^t) = \det(A)$ .

Per calcolare il determinante:

1) operare sulle colonne o sulle righe per creare una riga o una colonna con tanti zeri.

2) Sviluppare quella colonna o riga.

Es:

$$A = \begin{pmatrix} 2 & 4 & 1 \\ 3 & -1 & 3/2 \\ 5 & 7 & -3/2 \end{pmatrix}$$

$$\begin{aligned} \det A &= \det \begin{pmatrix} 0 & 4 & 1 \\ 0 & -1 & 3/2 \\ 8 & 7 & -3/2 \end{pmatrix} = 8 \det \begin{pmatrix} 4 & 1 \\ -1 & 3/2 \end{pmatrix} = \\ &= 8 \det \begin{pmatrix} 0 & 7 \\ -1 & 3/2 \end{pmatrix} = -8 \det \begin{pmatrix} -1 & 3/2 \\ 0 & 7 \end{pmatrix} \\ &= 56 \end{aligned}$$

$$\text{Ker } A = ?$$

$$A \rightsquigarrow \text{rref}(A) = R$$

sulle  
righe.

$$\Rightarrow \text{Ker } A = \text{Ker } R.$$

$$\begin{array}{ccc} & A & \\ \cdot & \xrightarrow{\quad} & \cdot \\ C & \downarrow \cong & \downarrow \cong \\ & R & \\ \cdot & \xrightarrow{\quad} & \cdot \\ & B & \end{array}$$

$$\begin{array}{ccc} & A & \\ \cdot & \xrightarrow{\quad} & \cdot \\ \parallel & & \downarrow \cong \\ \cdot & \xrightarrow{CA} & \cdot \end{array}$$

operazioni  
sulle  
righe

$$\begin{array}{ccc} & A & \\ \cdot & \xrightarrow{\quad} & \cdot \\ \cong & \downarrow C & \parallel \\ \cdot & \xrightarrow{AC^{-1}} & \cdot \end{array}$$

operazioni  
sulle  
colonne

## Utilizzo del determinante per il calcolo dell'inversa

Per  $m=2$ :  $A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$  è invertibile  $\Leftrightarrow \det(A) = ad - bc \neq 0$ .

In questo caso

$$A^{-1} = \frac{1}{\det(A)} \begin{pmatrix} d & -b \\ -c & a \end{pmatrix}$$

"Matrice  
Aggiunta di A"

Def: Dato  $m \geq 1$  ed una matrice quadrata  $A \in \text{Mat}_{m \times m}(\mathbb{K})$   
e dati un indice di riga  $i$  ed un indice  
di colonna  $j$ , definiamo il cofattore  $(i,j)$  di  $A$   
come il numero

$$C_{i,j} = C_{i,j}(A) = \det(A_{i,j}) (-1)^{i+j}$$

Oss:  $\det(A) = \sum_{j=1}^m a_{ij} C_{i,j} = \sum_{i=1}^m a_{ij} C_{ij}$

La matrice aggiunta ( $\sigma$  dei cofattori) di  $A$   
è la matrice che ha come componenti i cofattori  
e la denotiamo con  $\text{Agg}(A)$ :

$$\text{Agg}(A) = \begin{pmatrix} C_{11} & C_{12} & \dots & C_{1n} \\ \vdots & \vdots & & \vdots \\ C_{n1} & C_{n2} & \dots & C_{nn} \end{pmatrix} \in \text{Mat}_{n \times n}(\mathbb{K})$$

$$\underline{\text{Es:}} \quad A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$$

$$C_{11}(A) = +d$$

$$C_{12}(A) = -c$$

$$C_{21}(A) = -b$$

$$C_{22}(A) = +a$$

$$\text{Agg}(A) = \begin{pmatrix} d & -c \\ -b & a \end{pmatrix}$$

$$A^{-1} = \frac{1}{ad-bc} \begin{pmatrix} d & -b \\ -c & a \end{pmatrix} = \frac{1}{\det A} \text{Agg}(A)^t$$

Teorema : Sia  $A \in \text{Mat}_{m \times m}(\mathbb{K})$ . Allora

$$A \text{ Agg}(A)^t = \det(A) \mathbb{1}_n = \begin{pmatrix} \det(A) & 0 & \dots & 0 \\ 0 & \det(A) & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & \det(A) \end{pmatrix}$$

Es: ( $m=2$ )

$$\begin{pmatrix} a & b \\ c & d \end{pmatrix} \begin{pmatrix} d & -b \\ -c & a \end{pmatrix} = \begin{pmatrix} ad-bc & 0 \\ 0 & ad-bc \end{pmatrix} = \det(A) \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

✓

dim : Dobbiamo dimostrare

$$[A \text{ Agg}(A)^t]_{ij} = \begin{cases} \det(A) & \text{se } i=j \\ 0 & \text{se } i \neq j \end{cases}$$



$i=j:$

$$[A \text{ Agg}(A)^t]_i^i = A_i [\text{Agg}(A)^t]_i^i$$

$$= A_i \begin{pmatrix} c_{i1} \\ c_{i2} \\ \vdots \\ c_{im} \end{pmatrix} = a_{i1} c_{i1} + a_{i2} c_{i2} + \dots + a_{in} c_{in}$$

$$= \sum_{j=1}^m a_{ij} c_{ij} = \det(A)$$

$i \neq j$ :

$$\begin{aligned} \left[ A \operatorname{Agg}(A)^t \right]_i^j &= A_i (\operatorname{Agg}(A)^t)_j^i \\ &= A_i (\operatorname{Agg}(A)_j)^t \\ &= \sum_{k=1}^n a_{ik} c_{jk} \end{aligned}$$

Sia  $B$  la matrice che ha le stesse righe di  $A$  a parte la  $j$ -esima che poniamo uguale ad  $A_i$

$$B = \begin{pmatrix} A_1 \\ \vdots \\ A_i \\ \vdots \\ A_i \\ \vdots \\ A_n \end{pmatrix} \begin{matrix} \text{--- } i \text{ ---} \\ \text{--- } j \text{ ---} \end{matrix} \begin{pmatrix} A_1 \\ \vdots \\ A_i \\ \vdots \\ A_j \\ \vdots \\ A_n \end{pmatrix} = A$$

Sviluppiamo le righe  $j$

$$\begin{aligned}
 0 = \det(B) &= \sum_{k=1}^m b_{jk} C_{jk}(B) \\
 &= \sum_{k=1}^m a_{ik} C_{jk}(B) \\
 &= \sum_{k=1}^m a_{ik} C_{jk}(A)
 \end{aligned}$$

COR: Se  $A$  è invertibile,

$$A^{-1} = \frac{1}{\det(A)} \text{Agg}(A)^t$$

Formule  
di  
Cramer  
per  
l'inversa.

Es: Calcolare l'inversa di

$$A = \begin{pmatrix} 1 & -1 & 1 \\ 2 & 2 & 1 \\ 1 & -1 & 3/2 \end{pmatrix}$$

con la formula di Cramer.

Sol.:  $\det A = \det \begin{pmatrix} 0 & 0 & -1/2 \\ 2 & 2 & 1 \\ 1 & -1 & 3/2 \end{pmatrix} = 2 \neq 0$

$$C_{11} = + \det \begin{pmatrix} 2 & 1 \\ -1 & 3/2 \end{pmatrix} = 4 \quad C_{21} = - \det \begin{pmatrix} -1 & 1 \\ -1 & 3/2 \end{pmatrix} = 1/2 \quad C_{31} = + \det \begin{pmatrix} -1 & 1 \\ 2 & 1 \end{pmatrix} = -3$$

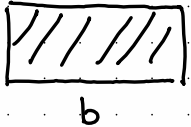
$$C_{12} = - \det \begin{pmatrix} 2 & 1 \\ 1 & 3/2 \end{pmatrix} = -2 \quad C_{22} = + \det \begin{pmatrix} 1 & 1 \\ 1 & 3/2 \end{pmatrix} = 1/2 \quad C_{32} = - \det \begin{pmatrix} 1 & 1 \\ 2 & 1 \end{pmatrix} = 1$$

$$C_{13} = + \det \begin{pmatrix} 2 & 2 \\ 1 & -1 \end{pmatrix} = -4 \quad C_{23} = - \det \begin{pmatrix} 1 & -1 \\ 1 & -1 \end{pmatrix} = 0 \quad C_{33} = + \det \begin{pmatrix} 1 & -1 \\ 2 & 2 \end{pmatrix} = 4$$

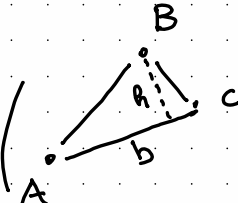
$$\Rightarrow A^{-1} = \frac{1}{2} \begin{pmatrix} 4 & 1/2 & -3 \\ -2 & 1/2 & 1 \\ -4 & 0 & 4 \end{pmatrix}$$

Applicazioni del determinante: Il determinante è  
un'area (se  $n=2$ ) "orientata".

Area:  $\text{Area} \left( \begin{array}{|c|} \hline \text{//////} \\ \hline \end{array} \right) = bh$

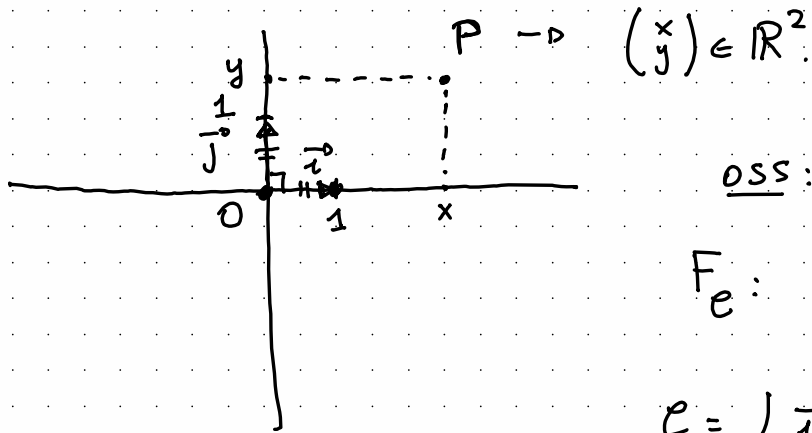


triangolo:  $\text{Area} \left( \begin{array}{c} B \\ \diagup \quad \diagdown \\ A \quad \quad c \\ \quad \quad \quad b \end{array} \right) = \frac{1}{2} b \cdot h$



$$\text{Area} (\triangle ABC) = \frac{bh}{2}$$

Identifichiamo  $\mathbb{R}^2$  con il piano cartesiano:



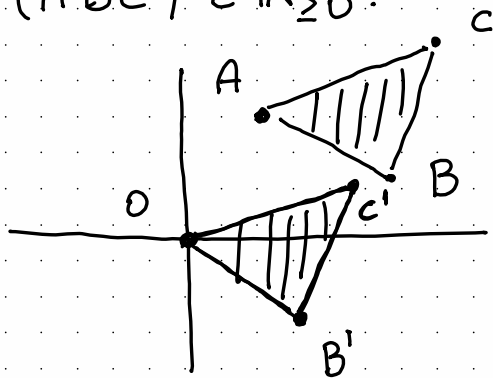
$$P \rightarrow (x, y) \in \mathbb{R}^2$$

oss:

$$F_e: \mathcal{V}_0^2 \xrightarrow{\cong} \mathbb{R}^2$$

$$e = \{ \vec{i}, \vec{j} \}$$

Area ( $\triangle ABC$ )  $\in \mathbb{R}_{\geq 0}$ .



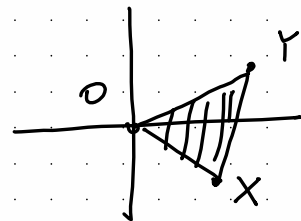
$$\text{Area}(ABC) = \text{Area}(OB'C')$$

dove

$$B' = B - A, \quad C' = C - A$$

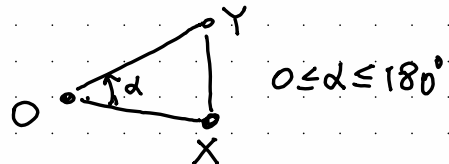
Area :  $\mathbb{R}^2 \times \mathbb{R}^2 \rightarrow \mathbb{R}_{\geq 0}$

$(x, y) \mapsto \text{Area}(\triangle OXY)$   
" "  
 $\text{Area}(x, y)$

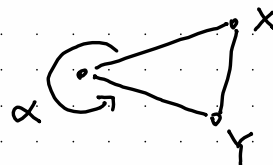


Definiamo la f.-ne  $A : \mathbb{R}^2 \times \mathbb{R}^2 \rightarrow \mathbb{R}$  come

$$A(x, y) = \begin{cases} \text{Area}(x, y) & \text{se} \\ -\text{Area}(x, y) & \text{se} \end{cases}$$



$0 \leq \alpha \leq 180^\circ$



$180^\circ \leq \alpha \leq 360^\circ$

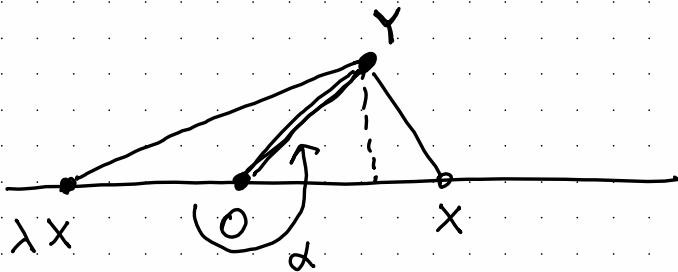
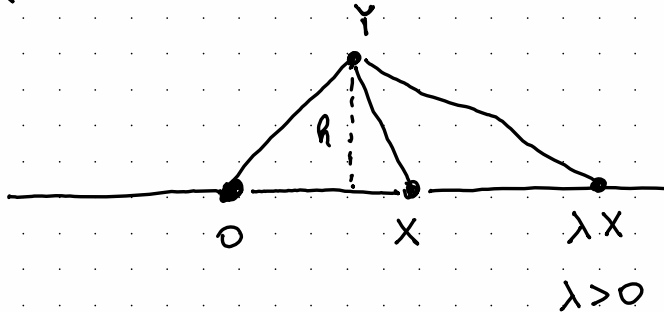
Proprietà:

$$A(y, x) = -A(x, y) \quad [\text{alternante}]$$

$$A(\lambda X, Y) = ?$$

$$\text{Area}(\lambda X, Y) = \lambda A(X, Y) \quad \text{se } \lambda > 0$$

$$= -|\lambda| A(X, Y) \quad \text{se } \lambda < 0$$



$$A(\lambda X, Y) = \lambda A(X, Y).$$





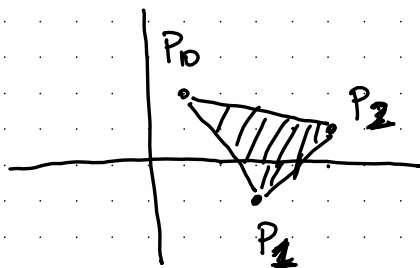
$$A(e_1, e_2) = \text{Area} \left( \begin{array}{c} \text{triangle} \\ \begin{array}{c} \text{vertices: } (0,0), (1,0), (0,1) \\ \text{right angle at } (0,0) \end{array} \end{array} \right) = \frac{1}{2}$$

$$\Rightarrow 2 A(x, y) = \det(x, y) \quad \Rightarrow \boxed{A(x, y) = \frac{1}{2} \det(x, y)}$$

$$\Rightarrow \text{Area}(x, y) = \left| \frac{1}{2} \det(x, y) \right|$$

Es: Calcolare l'area del triangolo di vertici

$$P_0 = \begin{pmatrix} 1 \\ 2 \end{pmatrix} \quad P_1 = \begin{pmatrix} 3 \\ -1 \end{pmatrix} \quad P_2 = \begin{pmatrix} 5 \\ 1 \end{pmatrix}$$

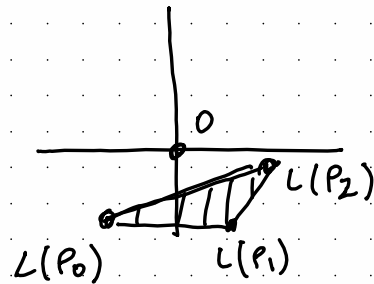
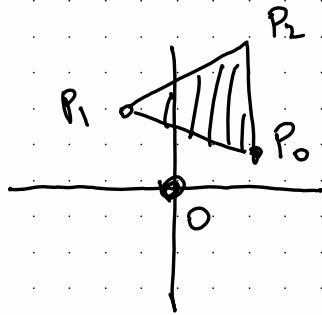


Sol.

$$\text{Area}(\triangle P_0 P_1 P_2) = \text{Area}\left(0, \begin{matrix} (2) \\ (-3) \end{matrix}, \begin{matrix} (4) \\ (-1) \end{matrix}\right) =$$

$$= \frac{1}{2} \left| \det \begin{pmatrix} 2 & 4 \\ -3 & -1 \end{pmatrix} \right| = \frac{1}{2} |-2 + 12| = 5.$$

$L: \mathbb{R}^2 \rightarrow \mathbb{R}^2$  linear,  $L = S_C$   $C \in \text{Mat}_{2 \times 2}(\mathbb{R})$



$$\begin{aligned} A(L(X), L(Y)) &= \frac{1}{2} \det(L(X) | L(Y)) \\ &= \frac{1}{2} \det(CX | CY) \\ &= \frac{1}{2} \det(C(X|Y)) \stackrel{\text{Binet}}{=} \frac{1}{2} \det(C) \det(X|Y) \end{aligned}$$

$$\text{Area}(L(X), L(Y)) = |\det(L)| \text{Area}(X|Y).$$

## Matrice di Vandermonde

Def: Dati  $x_1, \dots, x_n \in \mathbb{K}$  definiamo

$$\text{Van}(x_1, \dots, x_n) = V(x_1, \dots, x_n) = \begin{pmatrix} 1 & x_1 & x_1^2 & \dots & x_1^{n-1} \\ 1 & x_2 & x_2^2 & & x_2^{n-1} \\ \vdots & \vdots & \vdots & & \vdots \\ 1 & x_n & x_n^2 & & x_n^{n-1} \end{pmatrix} \in \text{Mat}_{n \times n}(\mathbb{K})$$

Esso si chiama matrice di Vandermonde associata ai "p.ti"  $x_1, \dots, x_n$ .

$$V(0, 1) = \begin{pmatrix} 1 & 0 \\ 1 & 1 \end{pmatrix}, \quad V(-1, -2) = \begin{pmatrix} 1 & -1 \\ 1 & -2 \end{pmatrix}$$

$$V(1, -1, 2) = \begin{pmatrix} 1 & 1 & 1 \\ 1 & -1 & 1 \\ 1 & 2 & 4 \end{pmatrix}, \quad V(-1, -1, 2) = \begin{pmatrix} 1 & -1 & 1 \\ 1 & -1 & 1 \\ 1 & 2 & 4 \end{pmatrix}$$

L'abbiamo già viste:

$$V = \mathbb{K}[x]_{\leq n-1}$$

$$\begin{array}{ccc}
 V & \xlongequal{\quad} & V \\
 F \downarrow & & \downarrow F_e \\
 \mathbb{K}^n & \xleftarrow{\quad} & \mathbb{K}^n
 \end{array}$$

$$\begin{array}{c}
 \text{Van}(x_1, \dots, x_n) \\
 \parallel \\
 \text{II}
 \end{array}$$

$$\begin{array}{cccc}
 \left( \begin{array}{ccc}
 1 & x_1 & x_1^2 \\
 1 & x_2 & x_2^2 \\
 \vdots & \vdots & \vdots \\
 1 & x_n & x_n^2
 \end{array} \right) & \dots & \left( \begin{array}{c}
 x_1^{n-1} \\
 x_2^{n-1} \\
 \vdots \\
 x_n^{n-1}
 \end{array} \right) \\
 \underbrace{\quad} & & \underbrace{\quad} \\
 F(1) & F(x) & F(x^2) & & F(x^{n-1})
 \end{array}$$

$$F(p(x)) = \begin{pmatrix} p(x_1) \\ p(x_2) \\ \vdots \\ p(x_n) \end{pmatrix}$$

$$F(p(x)) = \begin{pmatrix} p(x_1) \\ \vdots \\ p(x_n) \end{pmatrix} \quad \bar{e} \quad \text{lineare}$$

$$p(x) \in \text{Ker } F \quad \Rightarrow \quad p(x_1) = 0, p(x_2) = 0, \dots, p(x_n) = 0$$

$$\Rightarrow p(x) = q(x) (x-x_1)(x-x_2)\dots(x-x_n)$$

Se  $x_i \neq x_j \quad \forall i \neq j$  allora  $q(x) = 0 \Rightarrow p(x) = 0$

$\Rightarrow \text{Ker } F = \{0_V\} \Rightarrow F$   $\bar{e}$  un isomorfismo.

Se  $x_i = x_j$  per un certo  $i \neq j$ . allora

$$\text{Ker } F \neq 0.$$

Es:  $F(p(x)) = \begin{pmatrix} p(1) \\ p(1) \\ p(2) \end{pmatrix} \quad 0 \neq (x-1)(x-2) \in \text{Ker } F$

Quindi,

$\text{Van}(x_1, \dots, x_n)$  è invertibile  $\Leftrightarrow F$  è invertibile

$$\Leftrightarrow x_i \neq x_j \quad \forall i \neq j$$

In questo caso  $\text{Van}(x_1, \dots, x_n)$  è una matrice di cambiamento di base

$$\begin{array}{ccc} & V & \xlongequal{\quad} & V \\ F_B = F & \downarrow & & \downarrow F_e \\ & \mathbb{K}^n & \xrightarrow{\quad \text{Van}(x_1, \dots, x_n) \quad} & \mathbb{K}^n \end{array}$$

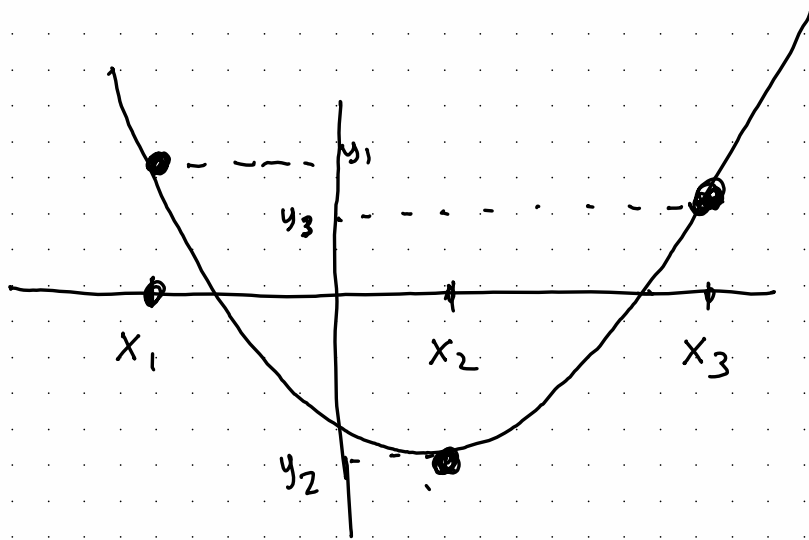
$$B = \{b_1, \dots, b_m\}$$

$b_1, \dots, b_n$  polinomi di Lagrange.

$$F(b_i) = e_i$$



$m=3$



$p(x)$  :  
polinomio  
interpolatore  
dei tre  
punti.

"  
Definizione

$$F^{-1} \left( \begin{pmatrix} y_1 \\ y_2 \\ y_3 \end{pmatrix} \right) = p(x) \quad \text{t.c.} \quad \begin{aligned} p(x_1) &= y_1 \\ p(x_2) &= y_2 \\ p(x_3) &= y_3 \end{aligned}$$

$\uparrow$   
ha grado  
 $\leq 2$